

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

Claim 1 (Canceled).

Claim 2 (Canceled).

Claim 3 (Canceled).

Claim 4 (Canceled).

Claim 5 (Canceled).

Claim 6 (Canceled).

Claim 7 (Canceled).

Claim 8 (Canceled).

Claim 9 (Canceled).

Claim 10 (Canceled).

Claim 11 (Canceled).

Claim 12 (Canceled).

Claim 13 (Currently Amended): A method for augmented reality guided instrument positioning, comprising the steps of:

rendering at least one graphics path guide for indicating a path for an instrument to follow to a target;

constructing and rendering at least one graphical axis marker ~~as a graphical marker~~;

identifying ~~the~~ at least one graphical axis marker on the instrument that marks an axis of the instrument, the axis disposed from a front portion to a back portion of the instrument, the front portion corresponding to the point on the target; and

aligning the at least one identified graphical axis marker with respect to the at least one graphics guide to align the instrument to the path.

Claim 14 (Canceled).

Claim 15 (Currently Amended): The method according to claim 13, further comprising the step of tracking the instrument to register the at least one identified graphical axis marker with respect to the axis of the instrument.

Claim 16 (Currently Amended): The method according to claim 13, further comprising the step of selecting an existing feature of the instrument to be a the at least one graphical axis marker.

Claim 17 (Currently Amended): The method according to claim 13, further comprising the step of designing the instrument to include ~~the~~ at least one physical axis marker.

Claim 18 (Currently Amended): The method according to claim 13, further comprising the step of adding ~~the~~ at least one physical axis marker to a structure of the instrument.

Claim 19 (Currently Amended): The method according to claim 13, wherein the at least one identified graphical axis marker is an elongated member.

Claim 20 (Currently Amended): The method according to claim 13, wherein the at least one identified graphical axis marker has a circular shape, and is centered on the axis of the instrument.

Claim 21 (Currently Amended): The method according to claim 13, wherein the at least one identified graphical axis marker is a cross comprised of an intersection of at least two lines, the intersection being centered on the axis of the instrument.

Claim 22 (Currently Amended): The method according to claim 13, wherein the at least one identified graphical axis marker comprises at least two axis markers for controlling alignment of the instrument along a line of sight.

Claim 23 (Previously Presented): A method for virtual reality guided instrument positioning, comprising the steps of:

defining a point on an actual target and an actual path to reach the point on the actual target;

tracking a pose of an actual instrument with respect to a pose of the actual target;

rendering a graphical representation of the actual instrument and the actual target point to obtain a virtual instrument and a virtual target point, respectively, the graphical representation being rendered with respect to a virtual viewpoint from which a virtual line of sight to the virtual target point coincides with a virtual path for the virtual instrument to follow during a positioning of the actual instrument to the point on the actual target, the virtual path corresponding to the actual path, the virtual instrument comprising a 3D structure for line of sight alignment, the 3D structure comprising a plurality of markers centered on and distributed along an axis of the virtual instrument; and

aligning the virtual instrument along the virtual line of sight to the virtual target point to align the actual instrument along the actual path.

Claim 24 (Original): The method according to claim 23, further comprising the step of moving the actual instrument along the actual path towards the point on the actual target, subsequent to said aligning step.

Claim 25 (Original): The method of claim 23, wherein the virtual target point has a circular shape.

Claim 26 (Original): The method of claim 25, wherein the circular shape is a ring.

Claim 27 (Canceled).

Claim 28 (Canceled).

Claim 29 (Previously Presented): The method of claim 23, wherein said plurality of markers comprise at least two rings, centered on an axis of the virtual instrument.

Claim 30 (Original): The method of claim 29, wherein the at least two rings have different diameters.

Claim 31 (Previously Presented): A method for virtual reality guided instrument positioning, comprising the steps of:

defining a point on an actual target and an actual path to reach the point on the actual target;

tracking a pose of an actual instrument with respect to a pose of the actual target;

rendering a graphical representation of the actual instrument and the actual target point to obtain a virtual instrument and a virtual target point, respectively, the graphical representation being rendered with respect to a virtual viewpoint from which a virtual line of sight to the virtual target point coincides with a virtual path for the virtual instrument to follow during a positioning of the actual instrument to the point on the actual target, the virtual path corresponding to the actual path;

choosing an orientation of the graphical representation around the virtual line of sight according to a pose of a user with respect to the actual target; and

aligning the virtual instrument along the virtual line of sight to the virtual target point to align the actual instrument along the actual path.

Claim 32 (Original): The method of claim 31, further comprising the step of determining the orientation such that east, west, north, and south correspond to right, left, forward, and backward, respectively, for the pose of the user in which the user faces the actual target, said determining step based on a selection.

Claim 33 (Original): The method of claim 31, wherein the orientation is dynamically adjusted according to a change of the pose of the user.

Claim 34 (Original): The method of claim 32, wherein the selection is dynamically adjusted with respect to the pose of the user.

Claim 35 (Previously Presented): A method for virtual reality guided instrument positioning, comprising the steps of:

defining a point on an actual target and an actual path to reach the point on the actual target;

tracking a pose of an actual instrument with respect to a pose of the actual target;

rendering a graphical representation of the actual instrument and the actual target point to obtain a virtual instrument and a virtual target point, respectively, the graphical representation being rendered with respect to a virtual viewpoint from which a virtual line of sight to the virtual target point coincides with a virtual path for the virtual instrument to follow during a positioning of the actual instrument to the point on the actual target, the virtual path corresponding to the actual path;

rendering graphical information about a distance between the actual instrument and the point on the actual target, the graphical information about the distance being overlaid onto the graphical representation; and

aligning the virtual instrument along the virtual line of sight to the virtual target point to align the actual instrument along the actual path.

Claim 36 (Canceled).

Claim 37 (Currently Amended): A method for virtual reality guided instrument positioning, comprising the steps of:

defining a point on an actual target and an actual path to reach the point on the actual target;

tracking a pose of an actual instrument with respect to a pose of the actual target;

rendering a graphical representation of the actual instrument and the actual target point to obtain a virtual instrument and a virtual target point, respectively, the graphical representation being rendered with respect to a virtual viewpoint from which a virtual line of sight to the virtual target point coincides with a virtual path for the virtual instrument to follow during a positioning of the actual instrument to the point on the actual target, the virtual path corresponding to the actual path; and

aligning the virtual instrument along the virtual line of sight to the virtual target point to align the actual instrument along the actual path. The method of claim 35, wherein the virtual target point and the virtual instrument are designed such that information corresponding to the distance between the actual instrument and the point on the actual target can be directly observed from an alignment of the virtual target point and the virtual instrument.

Claim 38 (Original): The method of claim 35, wherein said rendering step is performed according to a virtual camera with a wide angle lens.

Claim 39 (Currently Amended): The method of claim 35, wherein the virtual target point and the virtual instrument are each comprised of at least one ring centered on the target point respectively on the axis of the instrument, and a diameter of the at least one ring is dimensioned to achieve a pre-defined configuration together with the actual instrument when the actual instrument reaches the actual target.

Claim 40 (Original): The method of claim 23, wherein the graphical representation from the virtual viewpoint is combined with another graphical representation from another virtual viewpoint looking at the virtual path from a side thereof.

Claim 41 (Original): The method of claim 23, wherein said graphical representation from the virtual viewpoint is combined with an augmented reality view.